# *EFI Technology Inc. Engine Control System*

# **Hardware Reference Guide**



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## **Technical Support**

EFI Technology Inc. provides a first-line of technical support to its customers with regard to the installation and operation of the Engine Control Systems.

On site support is also available and will be charged on a time and expenses basis or through support contracts established with each customer. This will provide for the following services:

- Support Engineer attendance at all or an agreed to number of races.
- Ongoing system training.
- Assistance with system diagnostics.
- Access to emergency spare components.
- Unlimited telephone technical support.
- Access to restricted EFI web site areas that contain software updates.

## Contents

Hardware Reference Guide 1				
l	Documentation	2		
	Copyright Disclaimer Technical Support Contents Table of Figures	3 3 4		
:	Introduction	7		
	Overview	7		
Specifications	8	8		
	Connector Information	9		
	Autosport Connectors	0 1		
Installation		3		
	Connecting the ECU1	4		
	Power requirements1Connections1Connect/on methods1Backup battery1Battery Connections1ECU Systems1	.5 .6 .7		
:	Installation Information2	0		
	Harness Installation2 ECU Installation2 ECU Orientation	22		
Instrumentation		5		
	Connecting Sensors 2	6		
	Sensor types2	6		
:	Sensor Wiring2	7		
	Connecting a potentiometer2 Connecting a strain gauge2			

Appendix		30
	Contact Information	
	Address	
	Web Information	
	Software License Agreement	
	END-USER LICENSE AGREEMENT LIMITED WARRANTY	

# **Table of Figures**

Figure 1 – R8 ECU	7
Figure 3 - Autosport Free plug, type 6	10
-igure 4 - Autosport Inline receptacle, type 1	10
-igure 5 - Connector Part Numbering	11
-igure 6 - Battery Connections	16
Figure 7 - ECU Connections	18
Figure 8 - ECU Orientation	23
-igure 21 - Connecting a single ended input	.27
Figure 22 - Connecting a single ended input	28
Figure 23 - Connecting a differential input	28
Figure 24 - Connecting an RTD sensor	29
-igure 25 - Connecting a voltage output	29

# Introduction

## **Overview**

The EFI Engine Control Systems are designed for all levels of professional motorsports and available with up to 4, 8, 12 and 16 injector drives, 22 analog inputs and 4 digital channels. All analog inputs can be configured as 0-5 volt.

Some products have fully integrate chassis control such as transmission shifter, torque converter, shock adjustment, nitrous outputs, chute release etc.

Communications is via Bluetooth, CAN, USB, RS232 or current loop depending on the product and can interface to a wide range of 3<sup>rd</sup> party data logging systems.

All analog inputs are 0-5 volt or RTD inputs and compatible with most standard engine sensors. Strain gauge inputs require external in-line amplifiers with adjustable gains.

The system uses the latest Power to Win 9.0 software suite compatible with Win 8/10 64bit operating systems.



Figure 1 - R8 ECU

#### **More Information**

There is a wealth of additional information available on the EFI Technology web site at www.efitechnology.com. You can find, updates to the documentation, free downloads, technical articles, engineering information and much more.

# **Specifications**

## **Connector Information**

### Autosport Connectors

The EFI Engine Control System uses Deutsch Autosport AS, harsh environment connectors. The AS series is a range of medium and high density circular connectors designed to meet the stringent requirements of the motorsports industry.

Autosport connectors are manufactured using high strength aluminum alloys with black zinc coated shells. Contacts are copper alloy with gold plating and insulators are made with polyamide and fluorinated silicone.

Autosport connectors are used throughout the EFI system, its associated components and harnesses.

#### Features

- High density arrangements
- Contact sizes 16, 20 & 22
- Positive locking mechanism
- Conductive black zinc finish
- Interfacial and wire sealing
- 100% scoop proof with RFI grounding
- Integral shield and boot location
- In-line and hole mounting styles
- Environmentally sealed
- Standard gold plated contacts
- 5 keyway orientations (color coded)

#### **Contact rating**

Contact size	22	20	16
Current rating	5 amps	7.5 amps	20 amps
Max wire dia.	0.4mm	0.6mm	1.2mm

#### **Temperature rating**

-55 deg to +175 deg C

#### Vibration

Greater than 60g RMS in 3 axes

## **Connector Details**



Figure 2 - Autosport Free plug, type 6

Deutsch Autosport connectors use a rotating sleeve to lock the two halves of the connector together. To connect Deutsch Autosport connectors:-

- 1 Make sure that the two connectors are compatible by checking that the number of contacts and the position of the keyways is the same for both connectors.
- 2 Align the keyways, and bring the two halves of the connector together.
- 3 Apply light pressure to the connector as you slowly turn the knurled sleeve.
- 4 When the latches connect with the sleeve, keep turning until you hear the sleeve click.

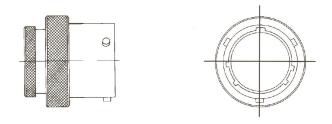
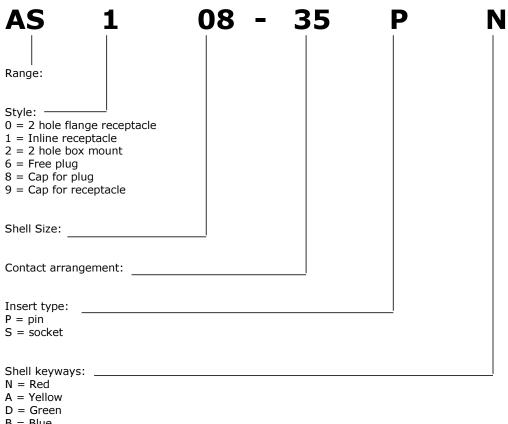


Figure 3 - Autosport Inline receptacle, type 1

The contacts of a Deutsch Autosport connector are labeled on the connector itself. The contact numbers are given on the outside and inside of the connector.

## Autosport part numbering

The part number is made up using the AS range reference followed by the style, the shell size, the contact arrangement, the insert type and the shell keyway e.g. AS108-35PN. The modification code is only applicable if a special modification has been made to the connector.



- B = Blue
- C = Orange
- U = Violet

Figure 4 - Connector Part Numbering

## **Contact arrangements**

Deutsch Autosport connector shell size and contact arrangements

The shell size and contact arrangement are shown below. Three sizes of contact are available: sizes 22, 20 and 16. The table below shows which sizes can be fitted.

Shell size	Contacts	Size 22	Size 20	Size 16
08	98	-	3	-
08	35	6	-	-
10	98	-	6	-
10	35	13	-	-
12	04	-	-	4
12	98	-	10	-
12	35	22	-	-
14	97	-	8	4
14	19	-	19	-
14	35	37	-	-
16	08	-	-	8
16	26	-	26	-
16	35	55	-	-
18	32	-	32	-
18	35	66	-	-
20	16	-	-	16
20	39	-	37	2
20	41	-	41	-
20	35	79	-	-
22	21	-	-	21
22	55	-	55	-
22	35	100	-	-
24	29	-	-	29
24	61	-	61	-
24	35	128	-	-

# Installation

# **Connecting the ECU**

The majority of vehicles have the negative terminal of the battery connected to the chassis and is commonly referred to as having a negative earth.

Battery connections are usually made through a Master Switch, which may be fitted in either the negative or positive, or both, supply leads from the battery. The Master Switch disconnects all electrical power in an emergency, and is required by the regulations governing most motor sports.

When connecting an ECU you should make sure that:

- the ECU remains powered up when the engine is turned off
- the ECU does not drain the car battery excessively
- the supply voltage to the ECU remains high enough for correct operation

When connecting an ECU to the battery:

- make all connections to, or as near as possible to, the battery terminals
- use a common point for connections to the battery
- keep the wire between the battery terminal and the connection point as short as is possible. Use heavy gauge wire, or braiding for this connection
- use 20-gauge or 22-gauge wire for connections between an ECU, and the connection point

CAUTION: Before making any connections to the battery, make sure you are confident with any harnessing that you have made. Remove power from the ECU before making any alterations.

## **Power requirements**

The ECU needs a supply voltage greater than 8.0 volts to start-up and between 10.0 volts and 18.0 volts to operate correctly. If the supply voltage is outside the 8.0 volts and 18.0 volts limits, the LCU will not function correctly.

Depending upon the loads that you have connected and number and type of sensors the current consumption is typically between 1 amp and 3 amps. The battery +VE and battery -VE supply lines are fitted with a 5 amp fuse inside the LCU.

### Connections

All system battery connections must only be connected to the battery at one point. Multiple connections to a length of wire or the chassis, will Introduce noise and reduce the integrity of sensor readings.

The optimum installation utilizes common connection points for the positive and negative terminals of the battery. Connecting equipment at a common point reduces the variation in supply voltage as current returns to the battery from other electrical components.

## **Connection methods**

The most common form of electrical system for vehicles consists of a battery an alternator and electric starter motor. Power to the electrical components is made from the battery through a master Switch that isolates the entire vehicle electrical system. Battery power is then directed to secondary switches for all other device connections.

If your vehicle has this type of electrical system, then connect your logging system using the arrangement shown below. Use 20 or 22 gauge twisted wire to the logger system.

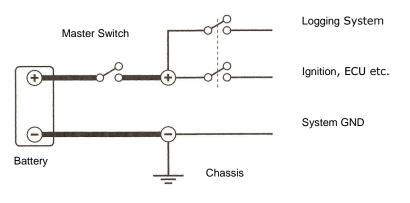


Figure 5 - Battery Connections

## **Backup battery**

Some vehicles fitted with an electrical starter motor may drop the battery to as low as 6 volts during starting conditions. The ECU will not function normally below 8 volts and it may be necessary to install a separate backup battery to maintain sufficient voltage under these conditions.

## **Battery Connections**

The ECU utilizes an internal common input power supply and grounding scheme with redundant connections. The battery connection and pins utilized are listed below.

NOTE: You must fit a backup battery if you are using safety critical or control applications. For further details refer to the section on fitting a backup battery.

#### **Connecting the ECU**

The ECU is connected to the battery using pins located on the 79 pin system connector. These battery connections provide all of the power to the ECU and their functions are listed below. It is recommended that at least 3 of the PWR GND pins are utilized for the battery connection.

#### **Battery connections**

Pin	Connection	Function	
77	PWR GND	Battery -	
78	PWR GND	Battery -	
79	PWR GND	Battery -	
-	-	-	
26	VBATT	Battery +	

The battery input connection is protected by a 5 amp thermal fuse. The input circuit is also protected against reversed battery polarity connections and transient voltages up to 35 volts.

### **ECU Systems**

If your vehicle is fitted with a data logger you can connect it to the ECU to enable them to share information. Data is typically shared using one of the defined ECU communications interfaces.

It is recommended that the ECU and logging system are connected to the battery using common ground connections. If your vehicle has this type of installation then connect the logging system and ECU using the arrangement shown below.

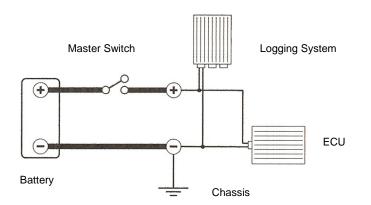


Figure 6 - ECU Connections

#### **Ground loops**

The ECU should be connected directly to the negative terminal of the battery but in some cases may be connected inadvertently to chassis ground causing a ground loop causing signal noise and incorrect sensor readings.

Ground loops can also occur if the shell of a connector touches the chassis and it may be necessary to fit rubber insulating material or boots over the connectors.

#### Testing for ground loops

Ground loops can be avoided by making direct connections to the battery. Before using your System, or if you are having problems with noise appearing in data from sensors, you should test for ground loops.

To test for a ground loop:

- 1. Disconnect the System connector from the car battery.
- 2. Measure the resistance between the ECU case and the chassis. If the resistance reading is low, then there is an electrical path to the chassis.
- 3. Starting with the sensor or junction box that is furthest away from the ECU, unplug ONE component at a time and measure the resistance between the ECU case and the chassis.
- 4. Repeat step 3 until the resistance reading is infinite.
- 5. Carefully check the component that you last disconnected for signs of shorting.

If the resistance reading is greater than 10k ohms, then your System is electrically isolated from the chassis. If you are still experiencing noise problems, then you should check that boots are fitted to all connectors, and that no connector is making contact with the chassis through vibration.

#### Avoiding ground loops

The most common source of a ground loop is a grounded sensor. Ensure that all sensors used are either isolated from the chassis (or engine), or if that is not possible then isolate the shield connection from that sensor.

# **Installation Information**

This section contains general information on how to install the Engine Control System, harnesses and associated equipment into your vehicle.

### **Harness Installation**

The harnesses manufactured by EFI Technology are made from spec 55 military airframe wire that can withstand temperatures up to 150°C. Harnesses are terminated with Deutsch Autosport connectors, are shielded and covered with Raychem heat shrink sleeve unless otherwise specified.

If you are making your own harnesses, then ask EFI for help with selecting suitable wire and connectors. Using poor quality wire and connectors may affect the performance and reliability of your logging System.

CAUTION: Manufacturing your own harnesses may void some of the terms and conditions of your product warranty.

#### Fitting harnesses

When fitting harnesses to your car, consider the following points:

- Care should be taken when routing wires near the engine. Make sure that your harnesses do not make contact with hot engine components such as exhaust pipes, manifolds, turbochargers or brake components.
- Excessive heat will burn the protective heat shrink layer, and may expose the inner shield and wires. This may lead to intermittent electrical faults and noise.
- When you install your harnesses, make sure that their position will not be affected by localized heating (heat soak) when the car is stationary.
- Remember that brake components frequently get very hot, and it will only be apparent after you have been running your car.

The easiest way to install harnesses is to make all connections to the ECU first, and then work away, towards any junction boxes, auxiliary equipment and sensors. Generally the harnesses become smaller and easier to route further away from the ECU.

#### Interference

In general, harnesses should not be routed next to sources of electrical interference i.e. ignition coils, plug leads, alternators, fuel pumps, telemetry equipment, especially antennas, and Ignitions. If you have to route a harnesses near any of these, try to avoid parallel runs.

#### Notes

- Allow harnesses to follow their natural curvature. Do not force them around very tight radii.
- When a harnesses passes through a hole in the chassis or bulkhead, make sure that there is no risk of it being cut or damaged.
- When using tie-wraps avoid attaching harnesses to sharp or abrasive objects.

#### Manufacturing

When making your own harnesses, use a spare length of cable, and route it exactly as the finished harness. Use off-cuts of cable to create branches and carefully mark the main harness where the branches occur. By spending time adjusting your dummy harness, you can achieve the optimum installation for your vehicle.

If you are supplying a harness specification to EFI, take measurements from the dummy harness to create an engineering drawing. Use the following standards when specifying measurements and dimensions to EFI.

Specify all dimensions:-

- to the end of connectors
- to the centerline of transitions
- to end of terminals or lugs

## **ECU Installation**

When installing the ECU you should consider the following points:

- The ECU is resistant to water, but after prolonged exposure, water, oil and fuel may eventually work their way inside the ECU.
- Select a position where the ECU will not be in constant contact with any fluid.
- The ECU must be protected from vibration. Use anti-vibration mounts.
- Make sure that air can flow over the ECU to keep it below +70°C.
- Do not place the ECU near sources of electrical interference e.g. Ignition coils, plug leads, alternators and telemetry antenna.

## **ECU Orientation**

#### Orientation

Some ECU's contains three identical accelerometers which are used to measure the lateral, longitudinal and vertical accelerations for each of the axes. The vertical accelerometer is a build option and may not be installed in your ECU.

It is particularly important that the lateral acceleration axis is in the correct orientation for the track mapping feature to function correctly in the analysis program. Please refer to the section later in this chapter if you need to change the standard ECU orientation. The standard ECU orientation and acceleration axes are shown in the figure below.

The ECU orientation is shown with the connectors pointing toward the front of the vehicle with the 66 pin system connector located on the right side of the housing.

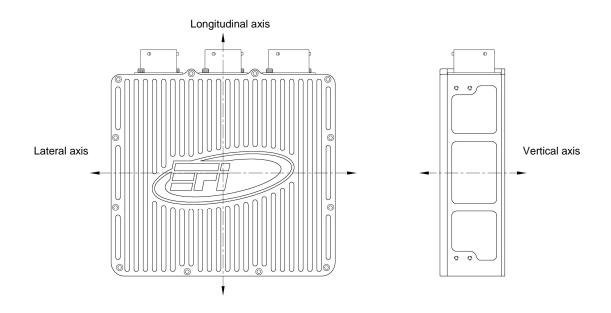


Figure 7 - ECU Orientation

#### Changing orientation

You can mount the ECU in a different orientation to the standard method. The three axes of acceleration (longitudinal, vertical and lateral) will still be measured, but by a different accelerometer to that used in the standard orientation. The channel names will need to be changed in the Power to Win software to correctly identify each channel.

The accelerometer channel names can be changed in the calibration editor window under channel calibrations. Please refer to the Help file or contact your EFI representative for further information on re-naming the acceleration channels.

#### Installing an ECU

- Select a suitable dry location for the ECU.
- Make sure that the area does not exceed 70°C.
- Localized heating effects will add to the ambient air temperature.
- Use the mounting lugs and vibration mounts to secure the ECU.
- When you have installed the ECU make sure that air can flow around it.

CAUTION: The ECU housing acts as a heat sink for its internal electronic components. It is Important that air can flow around the sides of the ECU.

# Instrumentation

## **Connecting Sensors**

The EFI engine control system uses an Autosport 5 pin connector standard for all sensor connections. The standard pinout for some different sensor types are given in the table below.

### **Sensor types**

5 pin sensor connect
----------------------

Single	Diff	RTD	Therm	Dig	
N/C	N/C	N/C	N/C	12V *	
5V	5V	N/C	N/C	5V	
SIG+	SIG+	RTD+	SIG+	SIG	
N/C	SIG-	RTD-	SIG-	N/C	
GND	GND	N/C	N/C	GND	
	N/C 5V SIG+ N/C	N/C N/C 5V 5V SIG+ SIG+ N/C SIG-	N/CN/CN/C5V5VN/CSIG+SIG+RTD+N/CSIG-RTD-	N/CN/CN/CN/C5V5VN/CN/CSIG+SIG+RTD+SIG+N/CSIG-RTD-SIG-	N/C N/C N/C N/C 12V *   5V 5V N/C N/C 5V   SIG+ SIG+ RTD+ SIG+ SIG   N/C SIG- RTD- SIG- N/C

\* See the section on voltage regulators for information about the supply current available for each of the regulated outputs.

#### Excitation

The sensor excitation voltage is typically 5 or 12 volts. The ECU also has an adjustable regulator set nominally at 8 volts and a fixed 20 volt 300mA output available.

#### Inputs

Differential means that there is a signal +ve and signal -ve input. Single ended means that the signal -ve is common with the signal ground input.

Generally only low current sensors should be used with single ended inputs. These types of input are suited to temperature or pressure sensors where the absolute accuracy is not required.

#### Mode

Unipolar means that the inputs can only measure positive signals. Bipolar means that the input can measure both positive and negative signals.

#### Gain

Unipolar channels can be configured with gains from 0 to 8. Bipolar channels can be configured with gains from 0 to 1200.

#### Types

There are two main types of sensor available, absolute and ratio-metric.

Absolute sensors are usually active sensors, such as accelerometers, which have an internal voltage reference or regulator and are unaffected by drift in the excitation voltage.

Ratiometric sensors, such as potentiometers or strain gauges, are affected by the excitation voltage. If you increase the excitation voltage the output signal will also increase proportionally.

In ratio-metric mode the ECU monitors the excitation voltage and compensates for any drift. This is useful for strain gauges or sensors using high gains where the excitation voltage may be higher to increase the output.

In ratio-metric mode the calibration is unchanged even when the excitation is increased. This means you can decrease the gain and improve the signal to noise ratio.

## **Sensor Wiring**

Wiring information for some different sensor types is given in the following figures.

## **Connecting a potentiometer**

Connect a potentiometer to a single ended input as shown below. If an amplifier is installed it should be configured with a gain of 1.

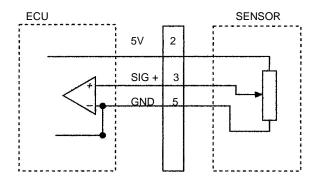


Figure 8 - Connecting a single ended input

Connect a potentiometer to a differential input as shown below.

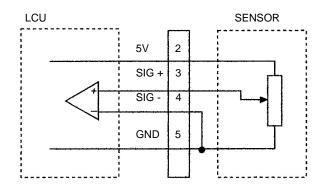


Figure 9 - Connecting a single ended input

## Connecting a strain gauge

Connect a strain gauge as shown below. The input amplifier should be configured with a gain from 100 to 1000 and typically with an offset of 2.5 volts.

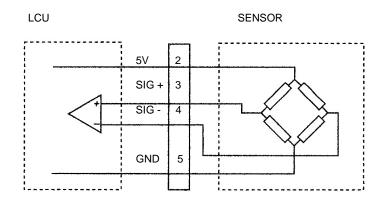
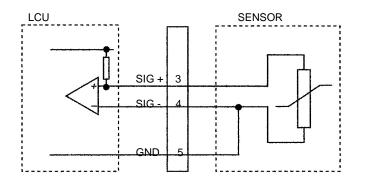
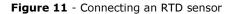


Figure 10 - Connecting a differential input

## **Connecting an RTD sensor**

Connect an RTD as shown below. The input amplifier should be configured with a gain of 100 and use a 3K92 pull-up resistor connected to 5 volts on the input.





## Connecting a voltage output

Connect 0-5 volt output sensor (e.g. pressure transducer) as shown below. Use either the 5v or 12v excitation voltage as recommended by the sensor manufacturer.

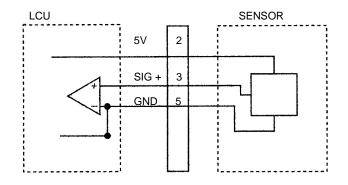


Figure 12 - Connecting a voltage output

# Appendix

# **Contact Information**

## Address

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## **Web Information**

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